

Please rate the following statements based on the task you have just completed.

Component	Scale Item	Strongly disagree	Disagree	Neutral	Agree	Strongly Agree
Robot's motion and pick-up speed	The way the robot moved made me uncomfortable					
	The speed at which the gripper picked up and released the components made me uneasy					
Safe Co-operation	I trusted that the robot was safe to cooperate with					
	I was comfortable the robot would not hurt me					
	The size of the robot did not intimidate me					
	I felt safe interacting with the robot					
Robot and gripper reliability	I knew the gripper would not drop the components					
	The robot gripper did not look reliable					
	The gripper seemed like it could be trusted					
	I felt I could rely on the robot to do what it was supposed to do					

## Reference

Charalambous, G., Fletcher, S., & Webb, P. (2016). The development of a scale to evaluate trust in industrial human-robot collaboration. *International Journal of Social Robotics*, 8(2), 193-209.